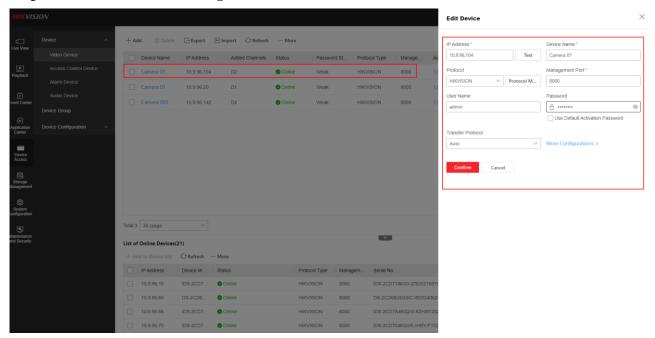
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How to use Self-Learning on GUI5.0

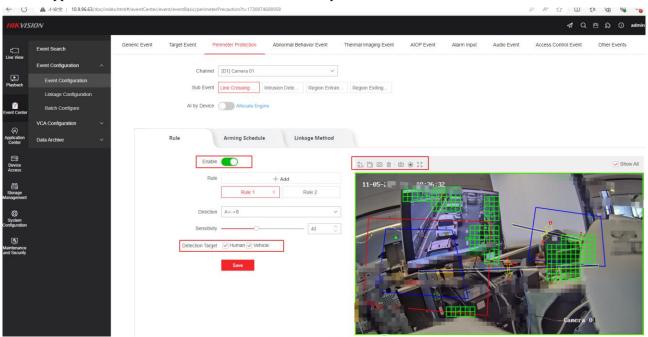
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Step 1: Add camera And configure Perimeter Event

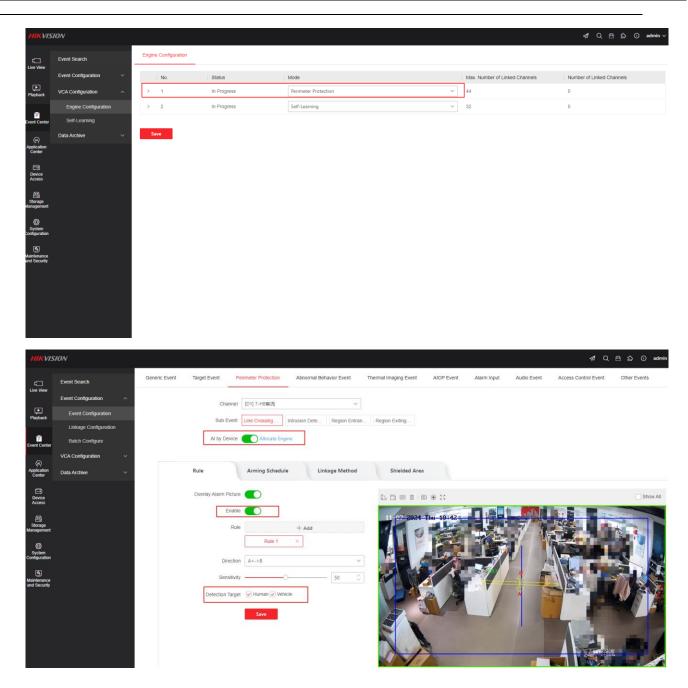


a) If IPC supports Perimeter Event, We can use the camera's perimeter function and select Humam or Vehicle



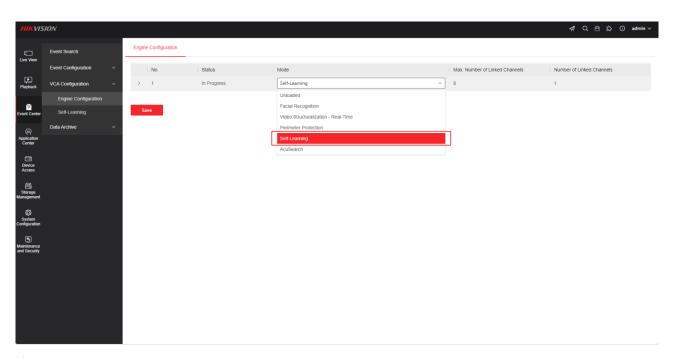
b) If ipc does not support Perimeter Event, NVR needs to have two engines, one of which switches to the Perimeter function

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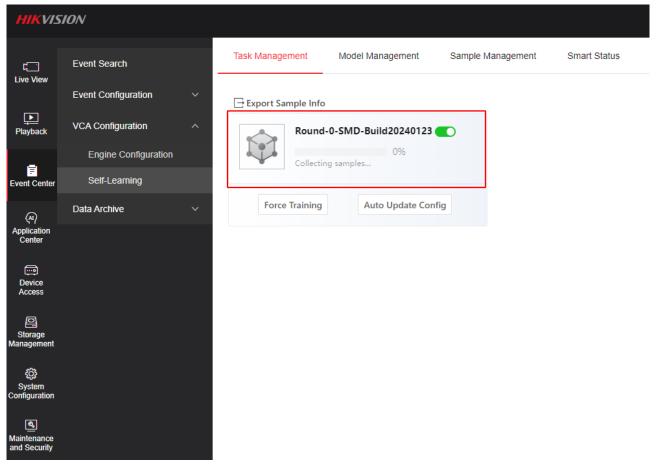


Step 2: Switch Engine to Self-learning

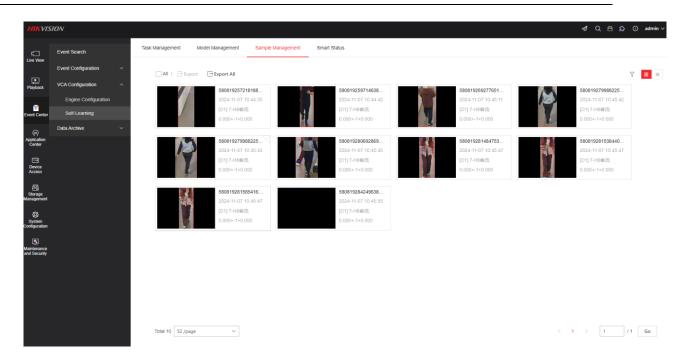
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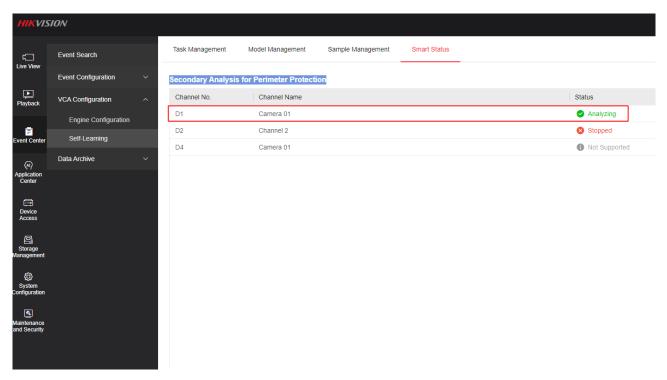
c) Check self-learning Progress and Secondary Analysis for Perimeter Protection



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The capacity of the self-learning engine for secondary analysis is 4 per second

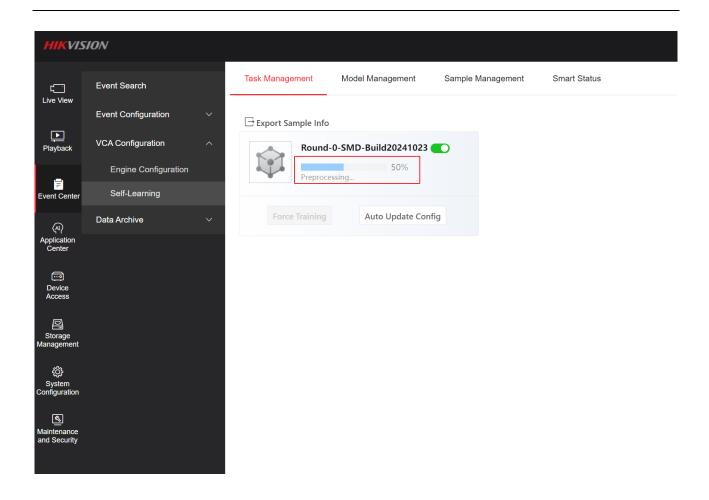


Step 3: Training model

Once the sampel collection is complete, the model will be preprocessing Conditions to start training(Any one condition)

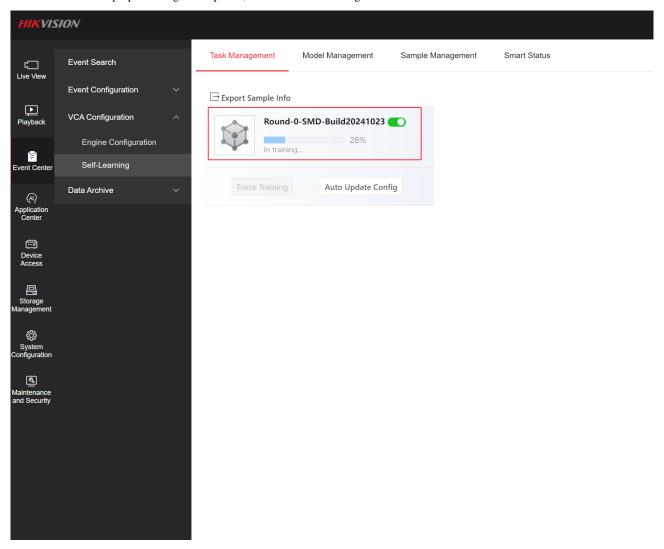
- 5W of samples in five days
- More than 5 days. Over 1W samples
- More than 30 days. Over 2,000 samples

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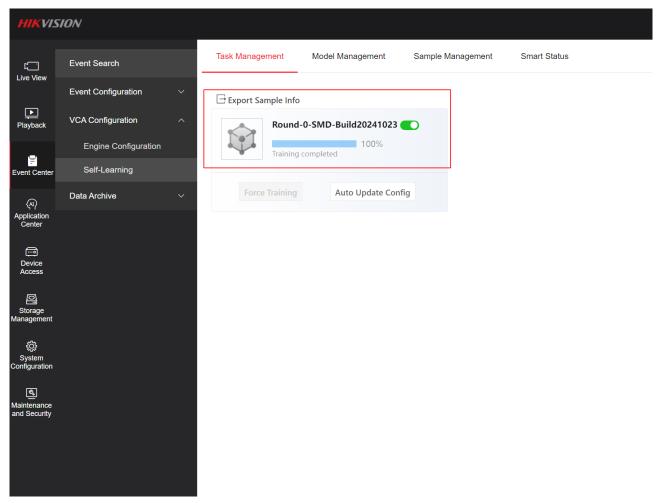
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After the preprocessing is completed, the model is in training

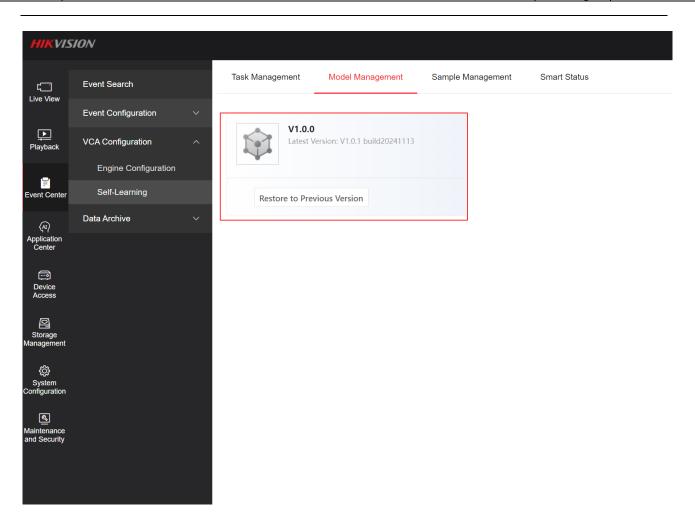


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Training Completed

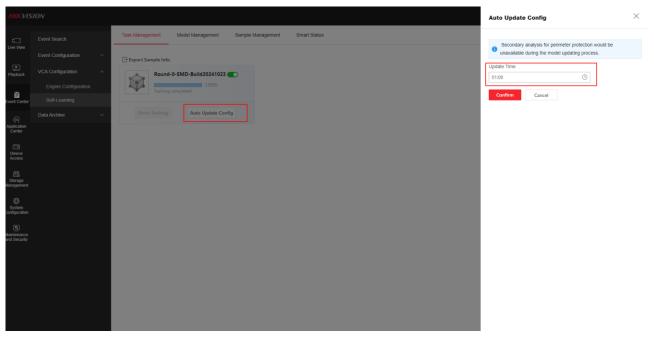


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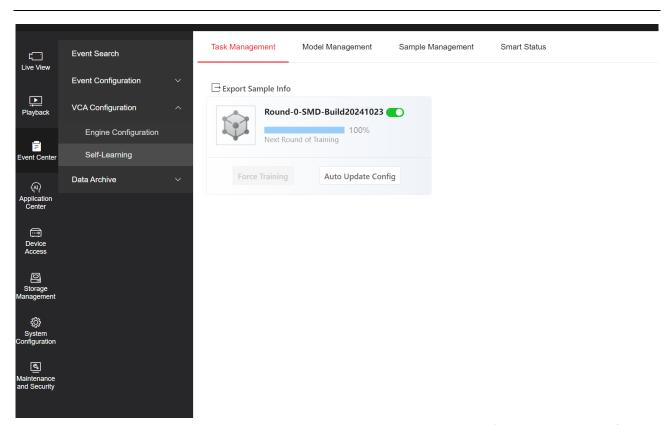


Step 4: Loading Model

We can set the update time or update the model at 1:00 by default. At the same time the next model starts training



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After training, the model is updated again, and the algorithm begins to collect samples (V1.0.0 to V1.0.1 to....) The more iterations of the model, the more accurate the algorithm will be

